

Lecture 12: Circuits for GS codes

1

12.1 Computing the error syndrome

$$C_2^\perp \leq C_1 = [n, k_1, d_1]$$

$$C_1^\perp \leq C_2 = [n, k_2, d_2]$$

$$G_1 = \left[\underbrace{\frac{H_2}{D_1}}_{n} \right]^{n-k_2} \Big\}^{k_1} \quad G_2 = \left[\underbrace{\frac{H_1}{D_2}}_{n} \right]^{n-k_1} \Big\}^{k_2}$$

Syndrome for bit-flip (σ_x^-) errors:

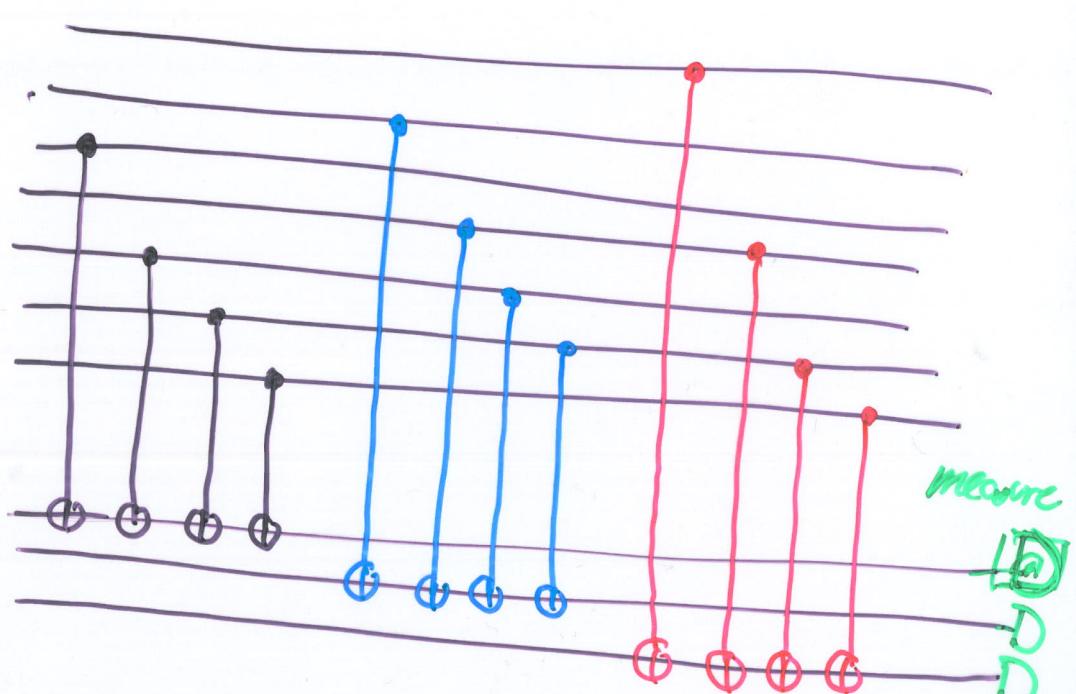
$$S_x: \quad |x\rangle \underbrace{|y\rangle}_{n-k_1} \rightarrow |x\rangle |x \cdot H_1^E + y\rangle$$

$$\text{CNOT: } \begin{array}{c} |x\rangle \\ |y\rangle \end{array} \xrightarrow{\text{CNOT}} \begin{array}{c} |x\rangle \\ |x+y\rangle \end{array}$$

$$\begin{pmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$H_1^E = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

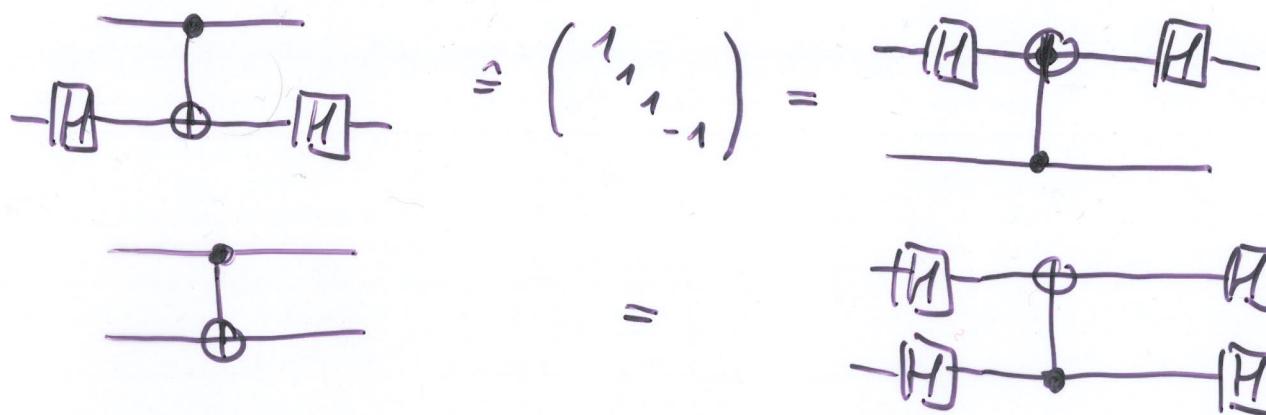
3
2
1



2

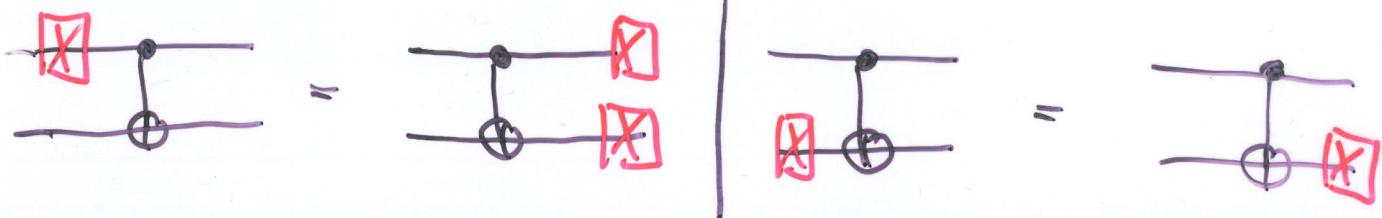
(2)

problem: This way of computing an error syndrome is not fault tolerant, as many control qubits are coupled to the same target qubit \Rightarrow single errors may spread over many locations

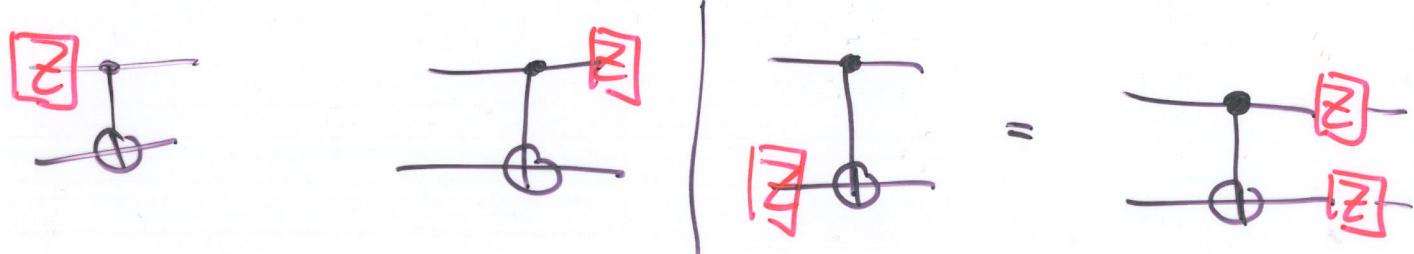


error propagation for CNOT:

X:

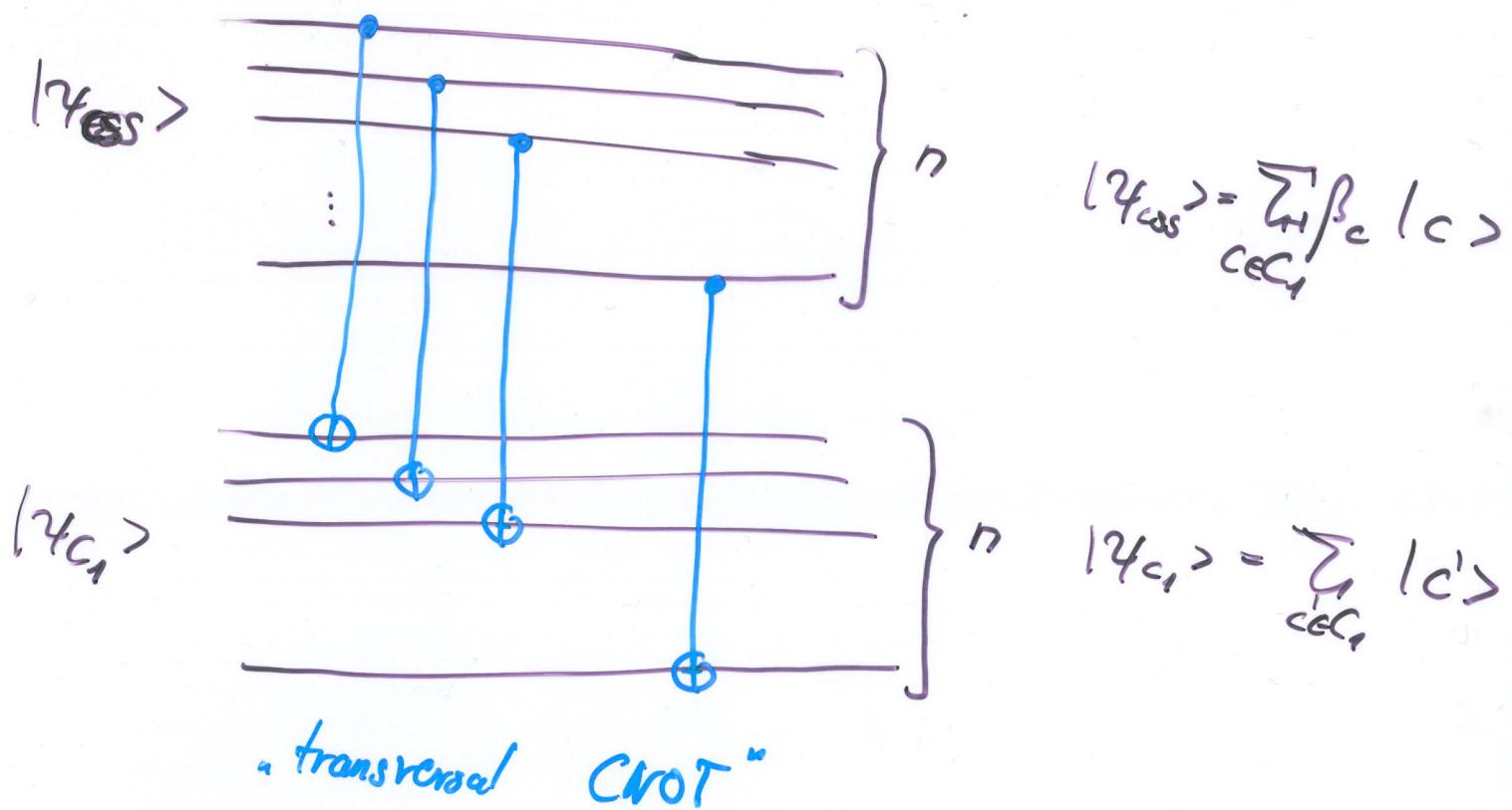


Z:



X propagates from control to target
 " " " target to control

12.2 Fault tolerant synchronous computation



$$(CNOT^{\otimes n}) \quad |\psi_{\text{ss}}\rangle \quad |\psi_{\text{c}}\rangle$$

$$= \sum_{e_x} \sum_{c \in C_1} \beta_c |c + e_x\rangle \quad \sum_{c' \in C_1} |c + c'\rangle$$

$\downarrow \text{measurement}$

random codeword $\tilde{c} \in C_1$

or $\tilde{c} + \tilde{e}_x$

then compute $(\tilde{c} + \tilde{e}_x) \cdot H_1^\dagger = \tilde{e}_x \cdot H_1^\dagger$
on a classical computer