

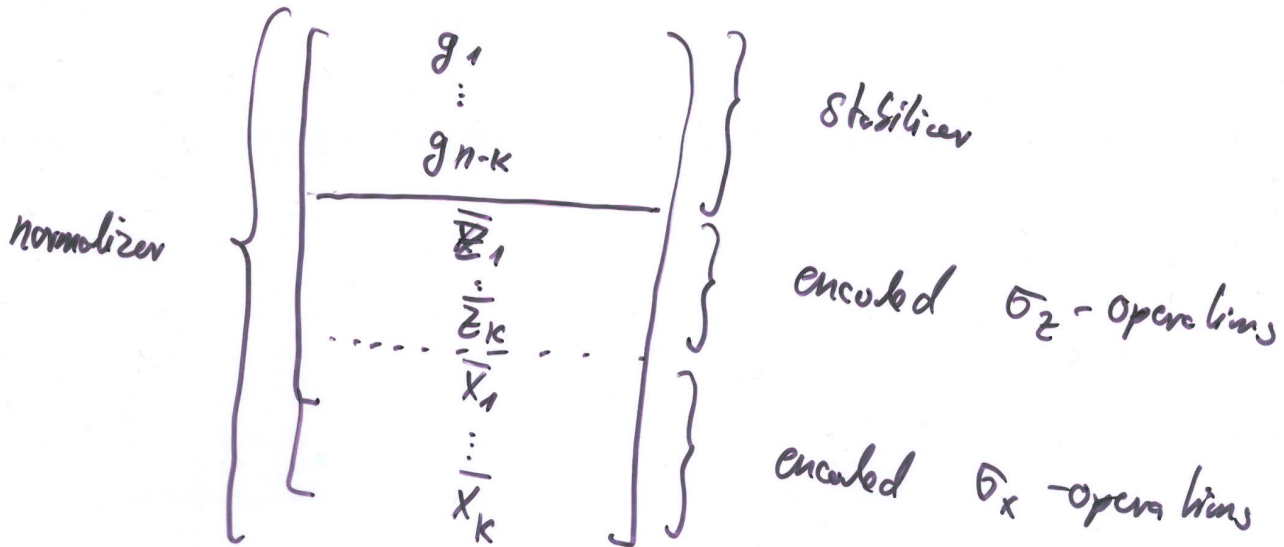
Lecture 16: Encoding of Stabilizer Codes

①

Stabilizer (group): $S = \langle g_1, \dots, g_{n-k} \rangle \subseteq \{id, \sigma_x, \sigma_z, \sigma_y\}^{\otimes n}$

Normalizer (group): $N = \{ \pi \in P_n : \pi \cdot S = S \cdot \pi \ \forall S \in S \}$

as classical codes



usually: stabilizer code is the joint $+1$ -eigenspace of all operators in S

more generally: for every generator g_i one can choose either the $+1$ or the -1 eigenspace to define the code

$\rightarrow \cdot 2^{n-k}$

"equivalent versions" of the code
 • decomposition of the full space into eigenspaces of S'

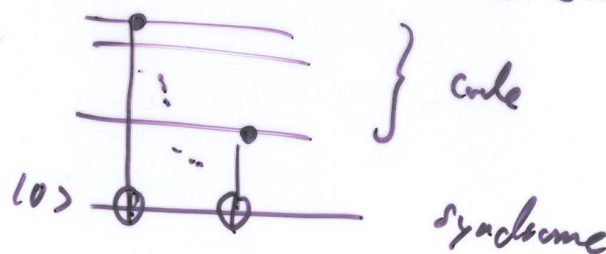
Any operator that changes the assignments of eigenvalues to the generators g_i can be detected by measuring the eigenvalue.

The sequence of $n-k$ eigenvalues yields a syndrome of the error.

16.1 Computing an error syndrome

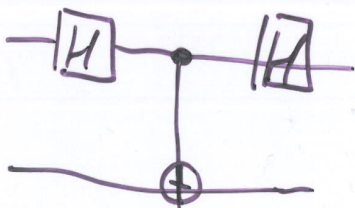
recall: CNOT-circuits

Compute the binary parity of the basis states using CNOTs

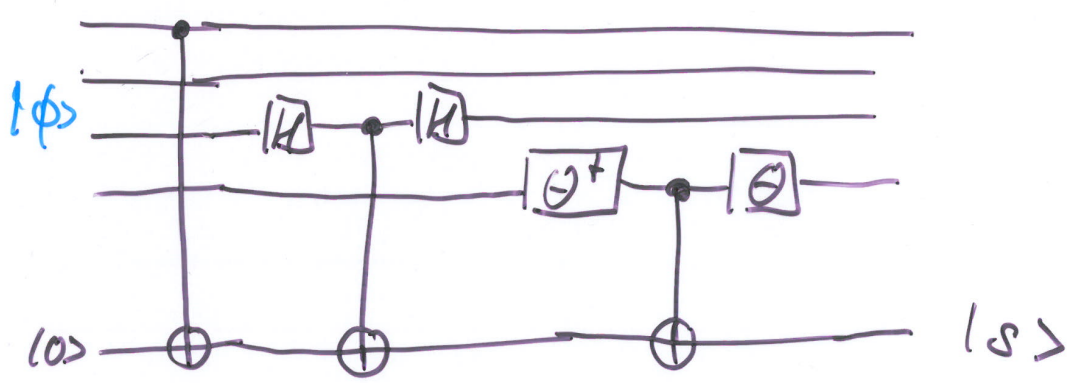


• CNOT "measures" of the eigenvalues of σ_z with eigenvector $|0\rangle$ and $|1\rangle$

→ use local transformations to "measure" the eigenvalues of σ_x and σ_y , e.g. for σ_x :

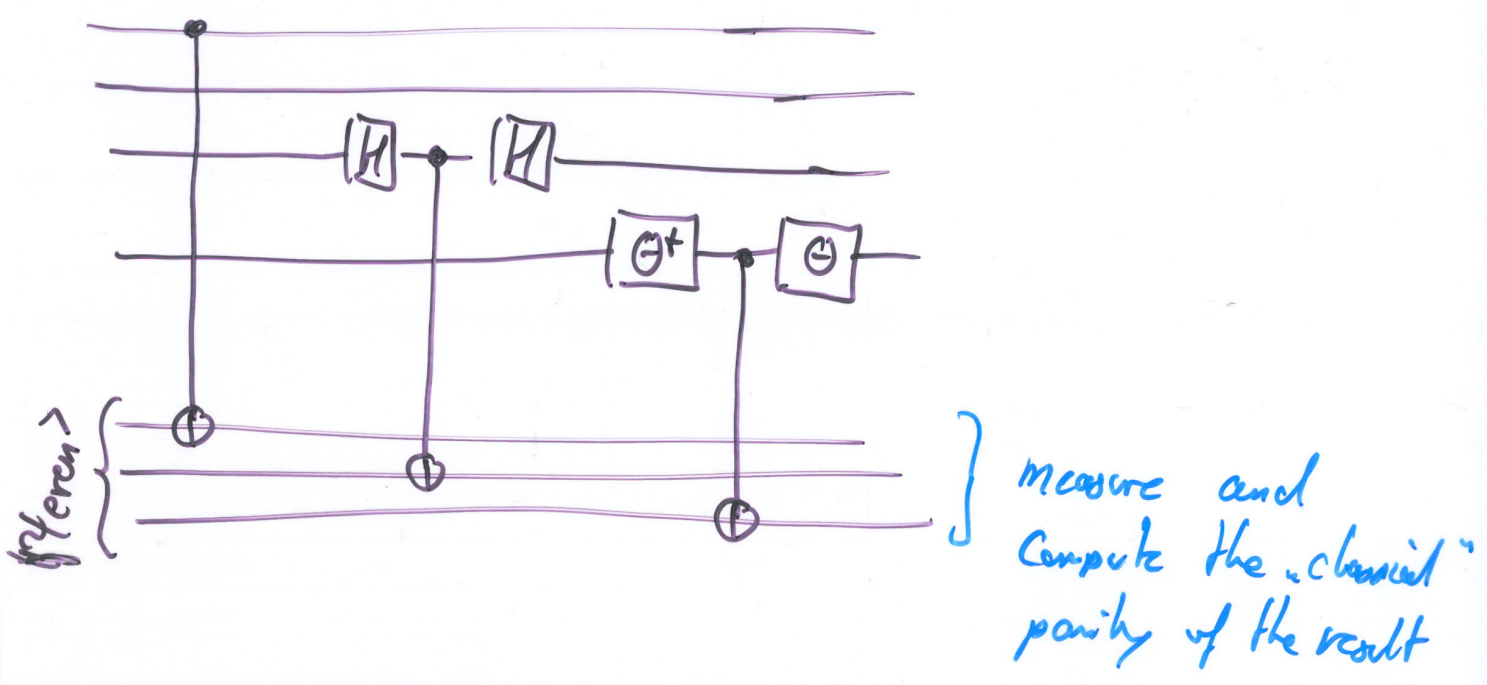


Example: $g = \sigma_z \otimes \text{id} \otimes \sigma_x \otimes \sigma_y$



$|s\rangle = |0\rangle$ if $g|\phi\rangle = |\phi\rangle$
 $|s\rangle = |1\rangle$ if $g|\phi\rangle = -|\phi\rangle$

fault tolerant version



16.2 Encoding Circuits

④

Version of Cleve & Gottesman

first idea: the code is stabilized by any element of S , i.e.

$$\forall |\psi_i\rangle \in \mathcal{C}: \forall s \in S: s|\psi_i\rangle = |\psi_i\rangle$$

$$\rightarrow \frac{1}{\sqrt{|S|}} \sum_{s \in S} s|\phi_0\rangle =: |\psi_0\rangle$$

$$s'|\psi_0\rangle = \sum_{s \in S} s's|\phi_0\rangle = \sum_{s \in S} s|\phi_0\rangle$$

$\Rightarrow |\psi_0\rangle$ is an element of the code (or the zero vector)

The operation $\frac{1}{|S|} \sum_{s \in S} s$ is a projection onto the code space.

Version 0 to realize a projection onto the code space:

- measure the eigenvalues $e_i \in \{+1, -1\}$ of the generators g_i
- the resulting state will be in the error space with error syndrome $(e_1, \dots, e_{n-k})$.
- "correct" the corresponding error

Observation:

S is an abelian group generated by $g_1, \dots, g_{n-k}$ with 2^{n-k} elements

$$\begin{aligned} \sum_{s \in S} s &= \prod_{i=1}^{n-k} (I + g_i) \\ &= (I + g_1)(I + g_2)(I + g_3) \cdot \dots \\ &= (I + g_1 + g_2 + g_1 g_2)(I + g_3) \cdot \dots \end{aligned}$$

remaining task:

Implement the projection operation $\frac{1}{2}(I + g_i)$ acting on some particular state by a unitary operation.

Case I: $I + \sigma_x$

$$\frac{1}{2}(I + \sigma_x) = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

$$\frac{1}{2}(I + \sigma_x) |0\rangle = \frac{1}{2}(|0\rangle + |1\rangle)$$

$$\frac{1}{\sqrt{2}}(H) |0\rangle = \frac{1}{\sqrt{2}}(|0\rangle + |1\rangle)$$

on the state $|0\rangle$, we can replace $I + \sigma_x$ by H

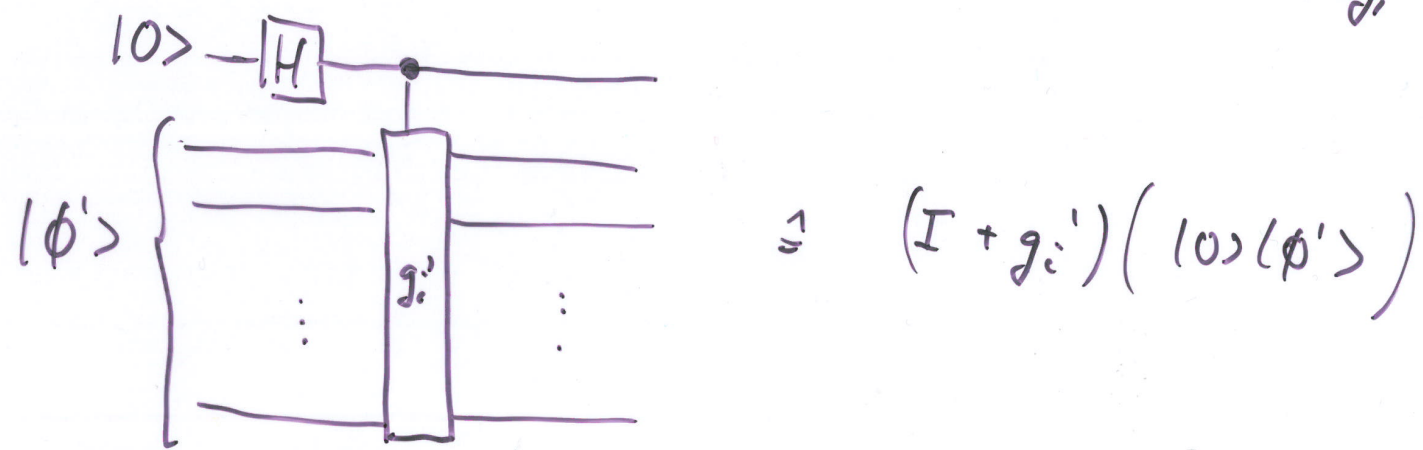
now $g_i = \sigma_x \otimes g_i'$

$$(I + g_i) = (I + \sigma_x \otimes g_i')$$

consider the state $|0\rangle \otimes |\phi'\rangle$

$$(I + g_i)(|0\rangle|\phi'\rangle) = |0\rangle|\phi'\rangle + |1\rangle(g_i'|\phi'\rangle)$$

→ we can replace σ_x by H
and g_i' by $|0\rangle\langle 0| \otimes I + |1\rangle\langle 1| \otimes g_i'$



Case II: $g_i = \sigma_y \otimes g_i'$

$$(I + \sigma_y) = \begin{bmatrix} 1 & -i \\ i & 1 \end{bmatrix}$$

on $|0\rangle$: $|0\rangle - i|1\rangle$

use $P = \begin{bmatrix} 1 & \\ & i \end{bmatrix}$ and $H = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$

→ replace $I + \sigma_y$ by $P^\dagger H$

Case III: $g_i = \sigma_z \otimes g_i$

$$\frac{1}{2}(I + \sigma_z) = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

$\Rightarrow$ the approach does not work for σ_z
 $\Rightarrow$ avoid σ_z in the construction!

additionally, we have to encode information!

- the state $|\psi_0\rangle$ corresponds to the encode state $|0 \dots 0\rangle$ of k encoded qubits
- we can use the operations $\bar{X}_i$ to obtain an encode state $|\underline{a}_1, \dots, \underline{a}_k\rangle$:

$$\begin{aligned} & \bar{X}_1^{a_1} \dots \bar{X}_k^{a_k} |0 \dots 0\rangle \\ &= \bar{X}_1^{a_1} \dots \bar{X}_k^{a_k} \left(\sum_{s \in S} s \right) |\phi_0\rangle \\ &= \left(\sum_{s \in S} s \right) \bar{X}_1^{a_1} \dots \bar{X}_k^{a_k} |\phi_0\rangle \\ &= \prod_i (I + g_i) \left(\prod_j \bar{X}_j^{a_j} \right) |\phi_0\rangle \end{aligned}$$

goal: implement the operation

$$\overline{x_j}^{a_j} | \dots a_j \dots \rangle$$

$j=1:$ $\overline{x_1}^{a_1} (|a_1\rangle \otimes |\phi'\rangle)$

Case I:

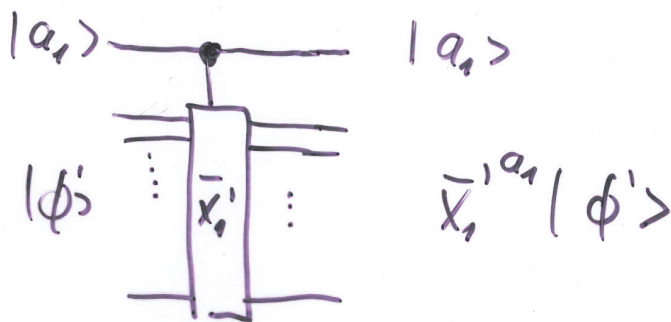
$$\overline{x_1} = \sigma_x \otimes \overline{x_1}'$$

Case II:

$$\overline{x_1} = \sigma_y \otimes \overline{x_1}'$$

two cases:

$a_1 = 1$: apply $\overline{x_1}'$ to the rest
 $a_1 = 0$: do nothing



→ we have realized

$$\overline{x}^{a_1} |0\rangle \dots |0\rangle$$

$$\Rightarrow \text{"pre-encoded state"} \overline{x_1}^{a_1} \dots \overline{x_k}^{a_k} (| \underbrace{0 \dots 0}_{k} \rangle | \underbrace{0 \dots 0}_{n-k} \rangle)$$

is replaced by an operation on the input state

$$|a_1 \dots a_k\rangle |0 \dots 0\rangle$$

②

We have to ensure that we always find a position in our generators g_i and encoded operation $\bar{X}_j$ such that

- i) the Pauli matrix at this position is either σ_x or σ_y
- ii) the state at this position is $|0\rangle$

$\Rightarrow$ compute a transformed "stabilizer + encoded X " matrix $\begin{bmatrix} S' \\ X' \end{bmatrix}$ in "upper triangular" form

idea: use row and column operations on the stabilizer + encoded X

$$G = \begin{bmatrix} 1 & 1 & \omega & 0 & \omega \\ 1+\omega & 0 & 1+\omega & \omega & \omega \\ 1+\omega & \omega & \omega & 1+\omega & 0 \\ 1 & \omega & 0 & \omega & 1 \end{bmatrix} = \begin{bmatrix} X & X & Z & I & Z \\ Y & I & Y & Z & Z \\ Y & Z & Z & \cancel{X} & I \\ X & Z & I & Z & X \\ \text{a} & \text{b} & \text{c} & \text{d} & \text{e} \\ X & I & Z & Z & I \end{bmatrix}$$

same encode operation

choose the operation $\bar{X}_j$ after transforming the stabilizer in "triangular form"

(10)

$$G' = \begin{bmatrix} 1 & 1 & \omega & 0 & \omega \\ \omega^2 & 0 & 1+\omega & \omega & \omega \\ \omega^2 & \omega & \omega & 1+\omega & 0 \\ 1 & \omega & 0 & \omega & 1 \end{bmatrix} = \begin{matrix} & X & Z^a & Z^b & Z^c & Z^e \\ \begin{bmatrix} X & X & Z & I & Z \\ Y & I & Y & Z & Z \\ Y & Z & Z & Y & I \\ X & Z & I & Z & X \\ X & I & Z & Z & I \end{bmatrix} \end{matrix}$$

↑
encoded X_1

without proof:

we can achieve a form of the stabilizer such that

- above the "diagonal" there are only I or Z
- on the diagonal, there are only X or Y

use the local Clifford operations H and Θ and row additions, i.e. multiplication of generators