

Lecture 20. Quantum Convolutional Codes

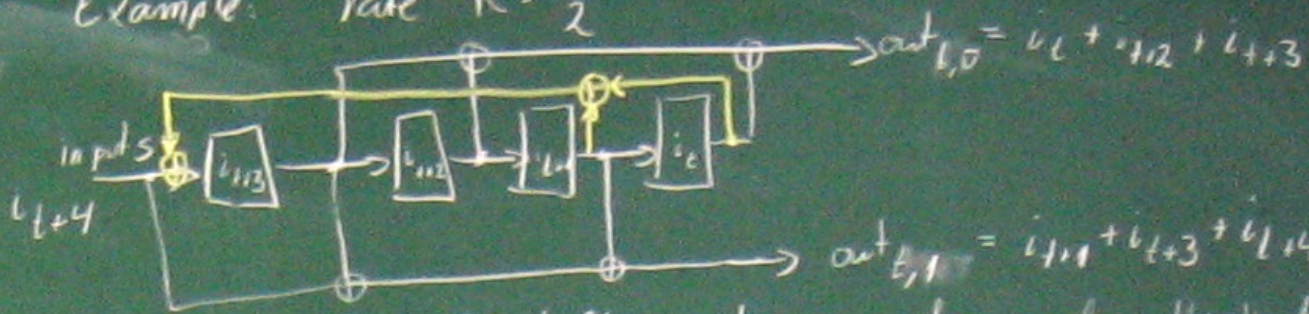
20.1 Motivation:

- Block codes encode a fixed number of qubits, good codes have a large blocklength n
good code: $\lim_{n \rightarrow \infty} \frac{d}{n} > 0, \lim_{n \rightarrow \infty} \frac{k}{n} > 0$
→ generators of the stabilizer group span many qubits ('non-local')
- goals - encode a stream of qubits
 - 'local' stabilizers
 - hopefully still good performance

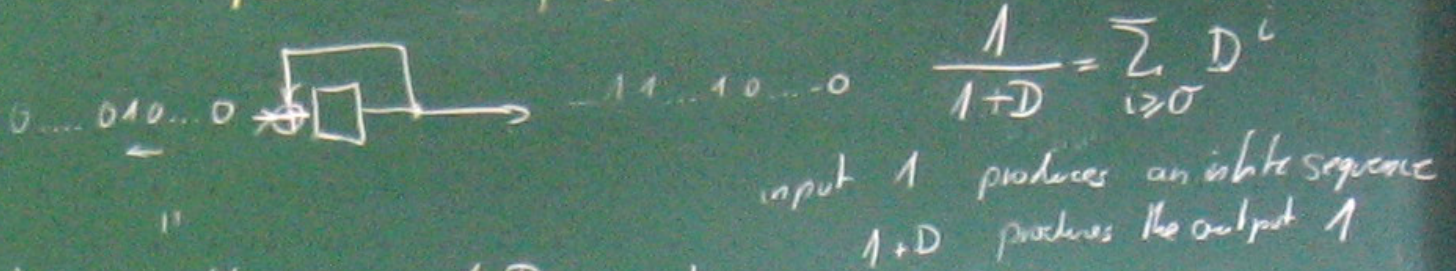
classical convolutional codes:

linear systems with finite memory, i.e. every output symbol depends linearly on the actual input symbol (or a group of inputs) and some previous inputs / the internal state of the encoder.

Example: rate $R = \frac{1}{2}$



linear feed-forward shift-register = polynomial multiplication
 feed-back = polynomial division



We use the powers of D as "time indicator", i.e.,

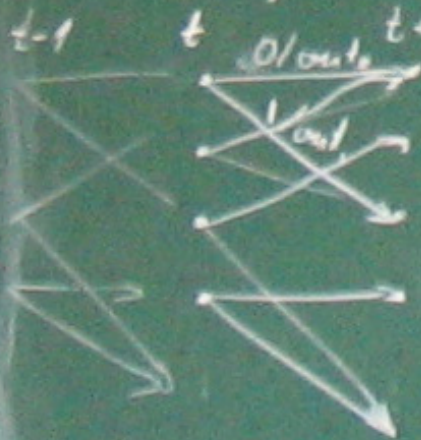
an input sequence $(a_0, a_1, \dots, a_L) \xrightarrow{\Delta} a_0 + a_1 D + a_2 D^2 + \dots + a_L D^L$

main idea for error correction:

The linear shift registers produce sequences which obey some linear 'local' constraints

=> diagram of the internal state and the output symbols

memory $m \Rightarrow 2^m$ internal states



- an edge between states s and s' labelled with the corresponding input/output
- every code sequence corresponds to path in this trellis diagram
- error correction: finding the closest path given an output sequence

2^m states

microscopic behaviour

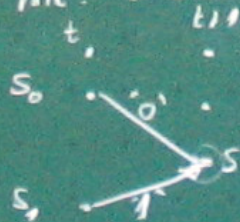
⇒ Viterbi algorithm

basic idea

compute for each state s the most likely sequence leading to this state, for memoryless channel,

we can have a 'local' update

rule: consider only the last transition



for every state, we have computed the most likely path up to time t

• weight of a path

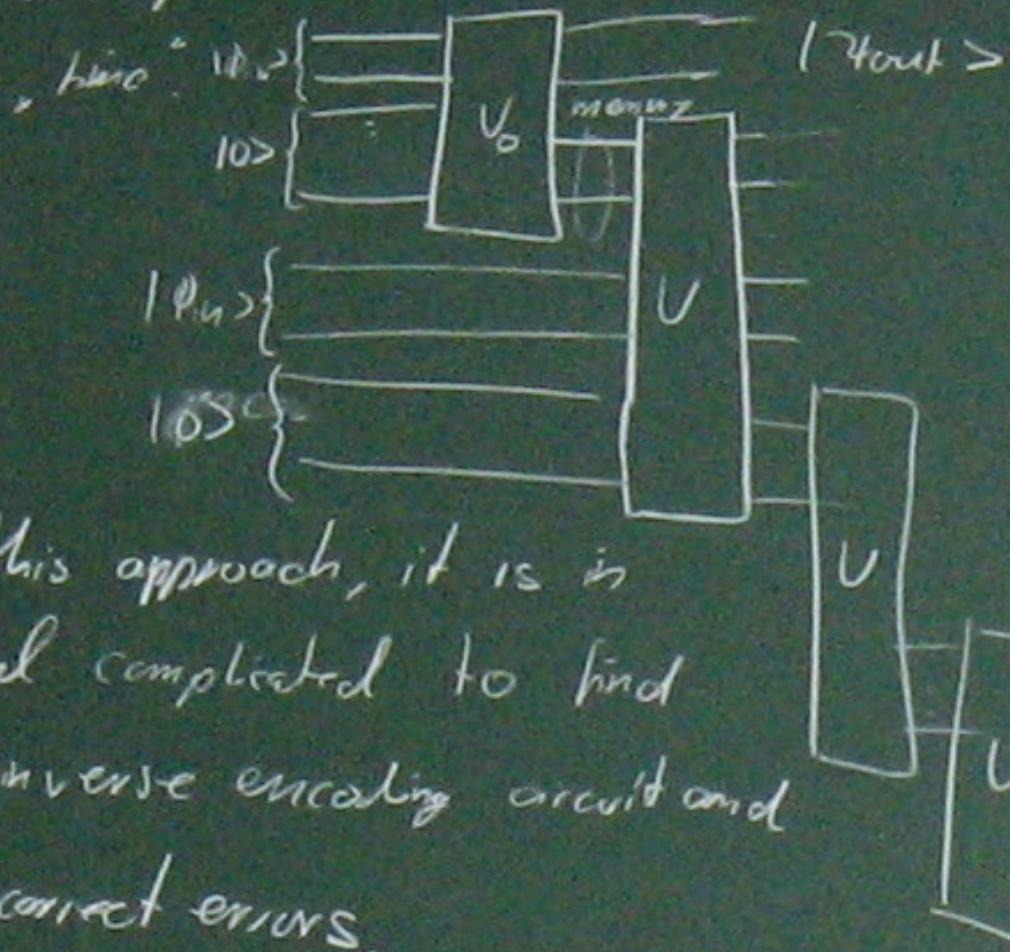
$$\text{wgt}(s_0 \rightarrow s) = \text{wgt}(s_0) + \text{wgt}('0')$$

$$\text{wgt}(s_1 \rightarrow s) = \text{wgt}(s_1) + \text{wgt}('1')$$

even with 'small' memory, classical convolutional codes have a good performance (used in many comm. systems)

2. Qubit 20 Quantum version

- a) use an operational analogue of shift-registers, e.g. use a fixed unitary (encoding circuit) and shift it in



b) 'use an analogue of local constraints,
i.e. stabilizers with finite support

Example: $S_1 = \dots \begin{matrix} III & XXX & XZY & III & III & \dots \end{matrix}$
 $S_2 = \dots \begin{matrix} III & ZZZ & ZYX & III & III & \dots \end{matrix}$

shifted stabilizers $S_1' = \dots \begin{matrix} III & XXX & XZY & III & \dots \end{matrix}$
 (by 3 qubits) $S_2' = \dots \begin{matrix} III & ZZZ & ZYX & III & \dots \end{matrix}$

$\Rightarrow$ define a semi-infinite stabilizer generated by S_1, S_2
and all shifts by multiples of three

$$G = \left[\begin{array}{cc|cc} XXX & XZY & & \\ ZZZ & ZYX & & \\ & XXX & XZY & \\ & ZZZ & ZYX & \end{array} \right] \Rightarrow \left[\begin{array}{ccc|ccc} 1+D & 1 & 1+D & 0 & D & D \\ 0 & D & D & 1+D & 1+D & 1 \end{array} \right] = \left[X(D) \middle| Z(D) \right]$$

The code is the joint +1-eigenspace of all operators.

max. degree of the polynomials + 1
 $\geq$ number of qubits involved in
 a syndrome measurement

Commutator conditions
 block codes: $X \cdot Z^t - Z \cdot X^t = 0$

Convolutional codes

$$X(D) Z(1/D)^t - Z(D) X(1/D)^t = 0$$

203 A bad example

$$G = \begin{bmatrix} Z & Z & & \\ & Z & Z & \\ & & Z & Z \\ & & & \ddots \end{bmatrix} = (0 \mid 1 + D)$$

↑
does not have
a polynomial inverse

→ joint +1 eigenstates are

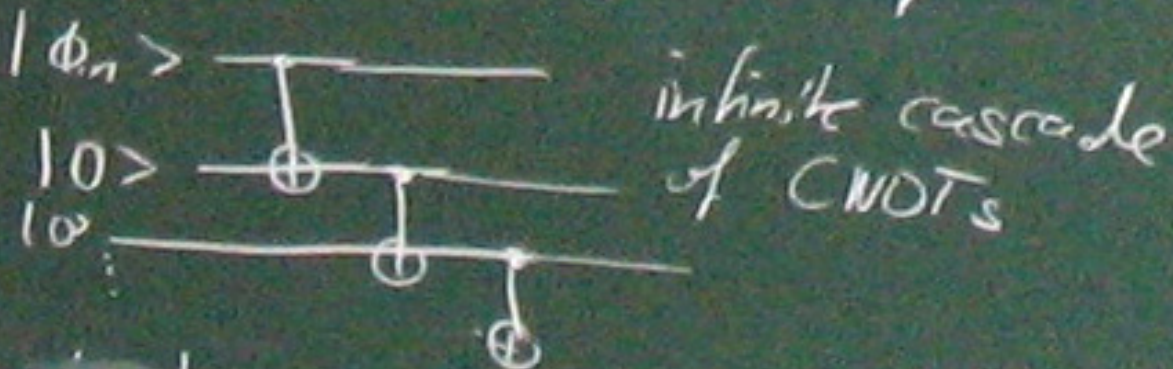
$$|\bar{0}\rangle = |00\rangle \quad >$$

$$|\bar{1}\rangle = |11\rangle \quad >$$

in particular: $|\bar{0}\rangle + |\bar{1}\rangle \in \mathcal{C}$

⇒ infinite "cat" state

encoding would be given by



⇒ try to avoid these infinite depth
circuits

20.4 Encoding circuits

based on transforming the stabilizer

$$[X(D) | Z(D)] \sim [0 | I | 0]$$

trivial block code
 $\hat{=}$ convolutional code without
memory

a) local operations $H = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$, $P = \begin{pmatrix} 1 & 0 \\ 0 & i \end{pmatrix}$

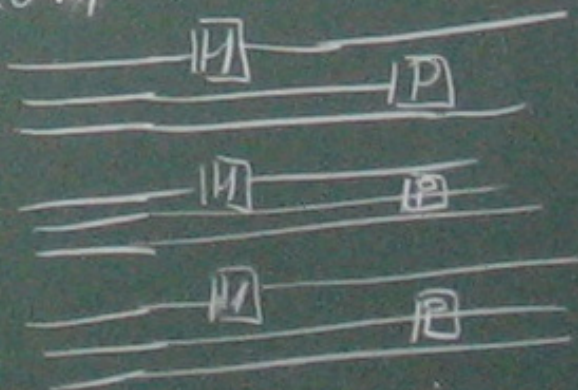
$\Rightarrow$ operations on the columns of $(X(D) | Z(D))$

given by $\tilde{H} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ $\tilde{P} = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$

$(X(D) | Z(D))$ corresponds to a semi-infinite
"block code" matrix

$\Rightarrow$ apply the gates H or P to all
shifted blocks

example: block length 3



References

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